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Simulation Example
of Object Hierarchy of
a Robotic Arm |

CoppeliaSim (V-REP)

*MIT cheetah robot
lands the running
jump* **3D Printed**

Robotic Arm

controlled with

Arduino \u0026 ROS

ROS Robotic

Platforms - Omni,

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Baxter in V-REP~~ *Pick
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with KUKA KR16
robot using v-rep
(CoppeliaSim) and
Matlab*

Control wheelchair
with a WebCam and
simulate with V-Rep
How this guy learned
how to build robots
without any formal

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Simulator: V-REP

Demo Video January

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~~simple robot in VREP~~

~~and controlling it~~

~~through ROS Vrep~~

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development environment, is based on a distributed control architecture: each object/model can be individually controlled via an embedded script, a plugin, a ROS or BlueZero node, a remote API client, or a custom solution. This makes CoppeliaSim very versatile and

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ideal for multi-robot
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~~Downloads~~—Coppelia
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PyRep PyRep is a toolkit for robot learning research, built on top of CoppeliaSim (previously called V-REP). NOTE: V-REP has recently been changed to CoppeliaSim.

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